

# Markov chains

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**Terminology.** Markov chain =  $M_c$ ; Transition probability matrix (матрица переходных вероятностей) =  $T_{pm}$

**Definition.** Distribution (распределение)  $\pi = (\pi_1, \dots, \pi_L)$  is called *stationary* for a  $M_c$  with  $T_{pm}$   $\Pi$  if  $\pi\Pi = \pi$ .

That is,  $\pi$  is a left eigenvector of  $\Pi$  with eigenvalue 1.

*Terminology: Stationary distribution = stationary measure = stationary state.*

**Remark.** We will often consider different Markov chains with the same  $T_{pm}$  (so, these Markov chains will differ only in their initial distribution  $p^{(0)}$ ). Abusing notation, we will often denote them by the same symbols (e.g. as  $\xi_0, \dots, \xi_T$ ). This is convenient since "key information" about a  $M_c$  is contained in the  $T_{pm}$  (so, in the graph if the  $M_c$ ) while initial conditions can be chosen in many different ways (think about the random walk or the Galton-Watson birth-death process).

# Lecture 7. Examples of stationary measure

## Lecture 7. Space of probability distributions

Let  $\mathcal{P}$  denote a space of (probability) distributions, i.e.

$$\mathcal{P} = \{p = (p_1, \dots, p_L) : \sum_{i=1}^L p_i = 1, \quad p_i \geq 0 \forall i\}.$$

Then  $\mathcal{P} \subset \mathbb{R}^L$  is a simplex. In particular,  $\mathcal{P}$  is a convex compact set in  $\mathbb{R}^L$ . For any vector  $v = (v_1, \dots, v_L)$  we denote

$$\|v\|_1 := \sum_{i=1}^L |v_i| \quad \text{— the } l^1\text{-norm of } v.$$

**Exercise.** Check that  $(\mathcal{P}, |\cdot|_1)$  is a complete metric space, where  $|\cdot|_1$  denotes a metric on  $\mathcal{P}$  generated by the  $l^1$ -norm.

## Lecture 7. Existence of a stationary measure

**Theorem 17.** *Any homogeneous Markov chain (with finite number of states) has a stationary measure.*

**Corollary 18.** Any stochastic matrix has a non-negative left eigenvector corresponding to eigenvalue 1.

*Proof 1 of the theorem: short but specific for our simple case.*

Brouwer fixed point theorem: a continuous mapping of a convex compact set to itself has a fixed point.

# Lecture 7. Bogoliubov-Krylov method

*Proof 2 (Bogoliubov-Krylov method): more complicated but VERY general.*

Let  $\rho^{(0)} \in \mathcal{P}$  be an arbitrary initial distribution. Then  $\rho^{(i)} = \rho^{(0)}\Pi^i$ .

Denote

$$\pi^k = \frac{1}{k} \sum_{i=0}^{k-1} \rho^{(i)} \in \mathcal{P}.$$

Since the sequence  $\pi^k$  is bounded in  $\mathbb{R}^L$ , it has a convergent subsequence  $\pi^{k_j}$ . Let

$$\pi = \lim_{j \rightarrow \infty} \pi^{k_j}.$$

Since  $(\mathcal{P}, |\cdot|_1)$  is complete,  $\pi \in \mathcal{P}$ .

Let us show that  $\pi$  is a stationary measure. Indeed,

$$\begin{aligned} \pi\Pi &= \left( \lim_{j \rightarrow \infty} \pi^{k_j} \right) \Pi = \lim_{j \rightarrow \infty} (\pi^{k_j} \Pi) = \lim_{j \rightarrow \infty} \frac{1}{k_j} \sum_{i=0}^{k_j-1} \rho^{(i+1)} = \lim_{j \rightarrow \infty} \frac{1}{k_j} \sum_{i=1}^{k_j} \rho^{(i)} \\ &= \lim_{j \rightarrow \infty} \frac{1}{k_j} \left( -\rho^{(0)} + \rho^{k_j} + \sum_{i=0}^{k_j-1} \rho^{(i)} \right) = \lim_{j \rightarrow \infty} \pi^{k_j} = \pi. \end{aligned}$$

**Definition.** A stochastic matrix  $A$  is called *ergodic* if there exists  $s \in \mathbb{N}$  such that all elements of the matrix  $A^s$  are strictly positive.

**Lemma 19.** A Tpm  $\Pi$  of a Mc is ergodic if and only if there is  $s \in \mathbb{N}$  such that the transition probabilities in  $s$  steps  $p_{ij}^{(s)} > 0$  for any  $i, j$ .

*Proof.* Accordingly to Lemma 11(?), the transition probabilities  $p_{ij}^{(s)}$  are elements of the matrix  $\Pi^s$ .

**Remark 20.** The property of a Tpm  $\Pi = (p_{ij})$  to be ergodic is NOT related to the explicit values  $p_{ij}$  but is related only to the structure of the graph of the corresponding Mc. That is, with positions of positive elements in  $\Pi$ .

# Lecture 7. Ergodic theorem (main result of the course, achtung!)

**Theorem 21.** (Ergodic Theorem) *Assume that a homogeneous Markov chain (with finite number of states) has ergodic  $T^m \Pi$ . Then it has a **unique** stationary measure  $\pi$  and there are constants  $C > 0$  and  $0 < \lambda < 1$  such that for any initial distribution  $p^{(0)}$  we have*

$$|p^{(n)} - \pi|_1 \leq C\lambda^n \quad \text{for any } n \geq 1.$$

Moreover,  $\pi_j > 0$  for every  $1 \leq j \leq L$ .

In particular, for any initial distribution  $p^{(0)}$  we have  $p^{(n)} \rightarrow \pi$  as  $n \rightarrow \infty$ .

$\Rightarrow$  Markov chain "forgets" initial conditions

$\Rightarrow$  Exponential convergence to equilibrium

**Corollary 22.** *Transition probability in  $n$  steps  $p_{ij}^{(n)}$  satisfy  $p_{ij}^{(n)} \rightarrow \pi_j$  as  $n \rightarrow \infty$ . This convergence is exponential, that is  $|p_{ij}^{(n)} - \pi_j| \leq C\lambda^n$  for any  $i, j, n$  and some  $C > 0$ ,  $0 < \lambda < 1$ .*

*Proof.* Let  $p^{(0)} = (0, \dots, 0, 1, 0, \dots, 0)$ . Then

$$p^{(n)} = p^{(0)}\Pi^n = (p_{i1}^{(n)}, \dots, p_{iL}^{(n)}) \rightarrow \pi.$$



# Lecture 7. Proof of the ergodic theorem. Preliminaries

**Notation:** For a vector  $v \in \mathbb{R}^L$  we denote  $\sum_+ v_j := \sum_{j: v_j > 0} v_j$ .

**Lemma 23.** Let  $p, q \in \mathcal{P}$ . Then  $|p - q|_1 = 2 \sum_+ (p_j - q_j)$ .

*Proof.* Since  $\sum_{j=1}^L (p_j - q_j) = 1 - 1 = 0$ , we have  $\sum_+ (p_j - q_j) = -\sum_- (p_j - q_j)$ . Consequently,

$$|p - q|_1 = \left( \sum_+ - \sum_- \right) (p_j - q_j) = 2 \sum_+ (p_j - q_j).$$

## Proof of the ergodic theorem:

The main idea is to show that the mapping  $\Pi^s$  is a contraction on  $(\mathcal{P}, |\cdot|_1)$ .

